

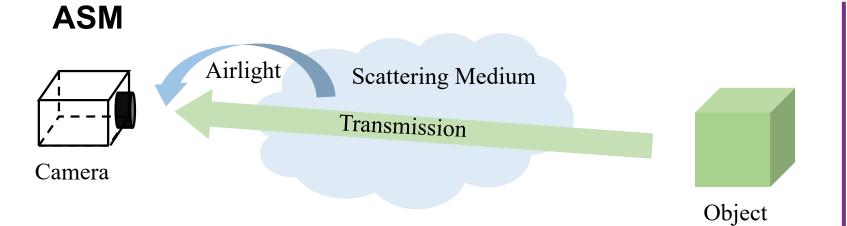


SynFog: A Photo-realistic Synthetic Fog Dataset based on End-to-end Imaging Simulation for Advancing Real-World Defogging in Autonomous Driving



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Motivations



- Fail to consider accurate global illumination and the actual imaging process.
- Disparity between synthetic and real-world foggy images, limited robustness.

Contributions

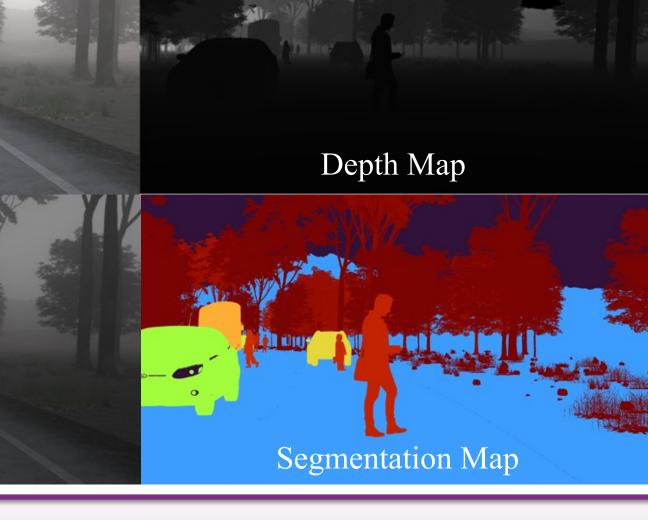
End-to-end foggy image simulation pipeline:

- a. Accurate light transportation in scattering medium
- b. Physical characteristics of optics and sensor

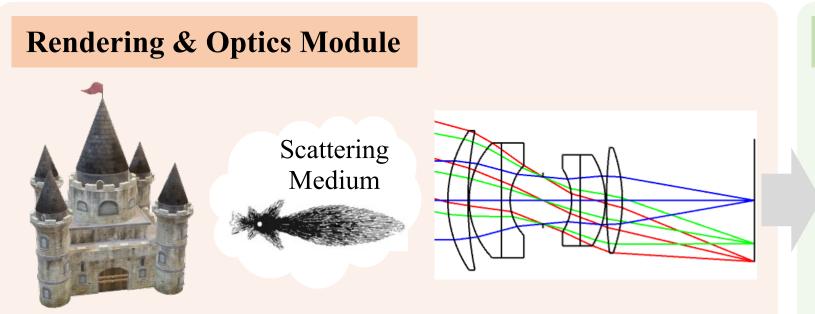
SynFog dataset:

- a. Both skylight and active lighting conditions
- b. Three levels of fog density
- c. Pixel-accurate depth data and segmentation labels

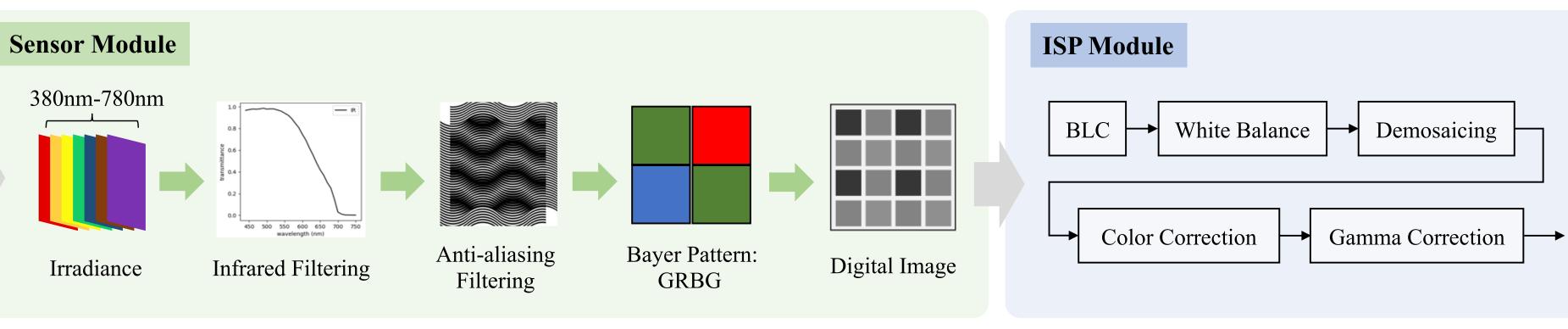




End-to-end Foggy Image Simulation Pipeline

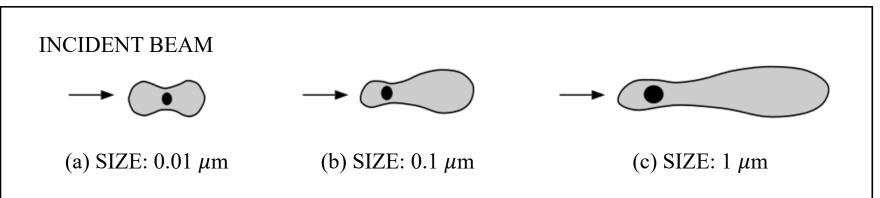






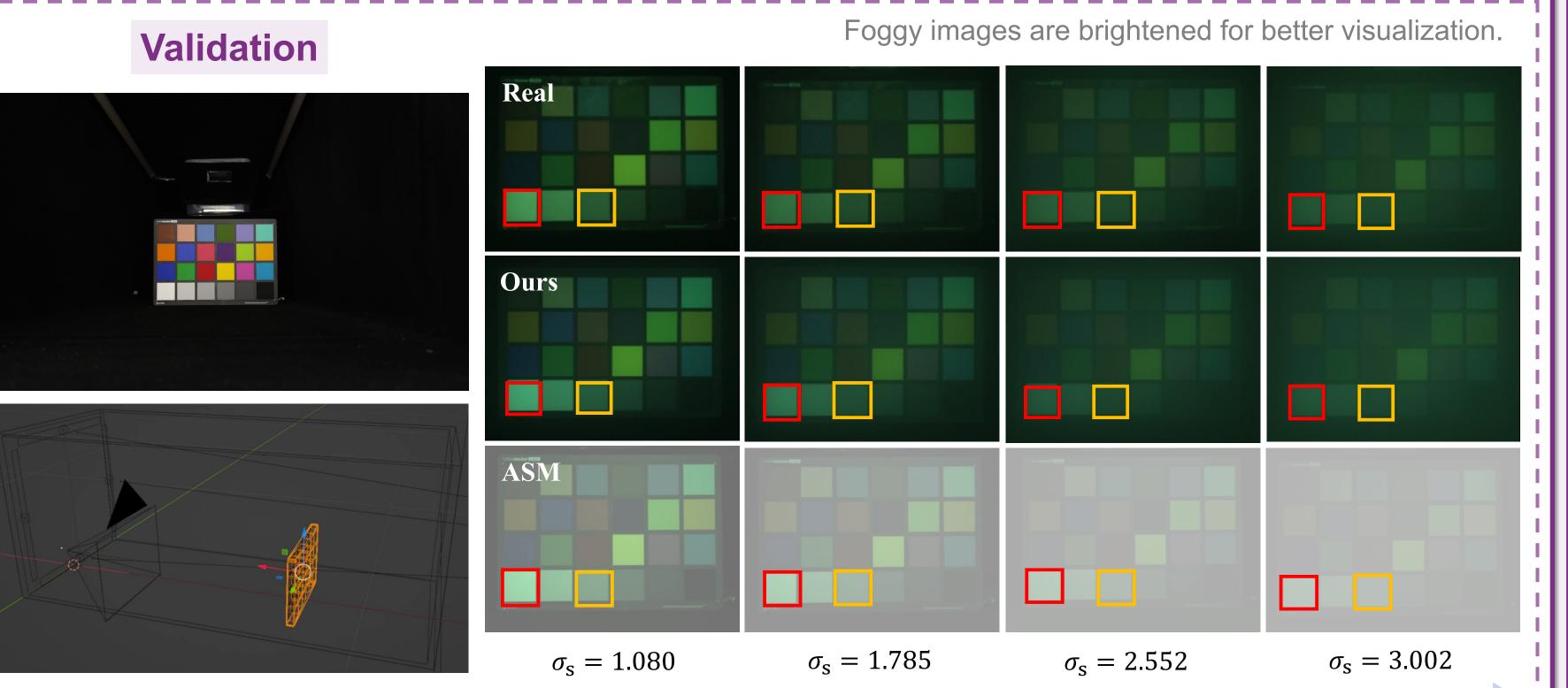
Foggy Scene Rendering

CONDITION	PARTICLE TYPE	RADIUS (µm)	CONCENTRATION (cm^{-3})	
AIR	Molecule	10^{-4}	10 ¹⁹	
HAZE	Aerosol	$10^{-2} - 1$	10 ³ - 10	
FOG	Water Droplet	1 - 10	100 - 10	
CLOUD	Water Droplet	1 - 10	300 - 10	
RAIN	Water Drop	10 ² - 10 ⁴	$10^{-2} - 10^{-5}$	



Henyey and Greenstein Phase Function:

$$p_{\rm HG}(\cos \theta) = \frac{1}{4\pi} \frac{1 - g^2}{(1 + g^2 + 2g(\cos \theta))^{3/2}}$$



Transferability across the Real-to-Virtual Gap



put	Foggy Citysca

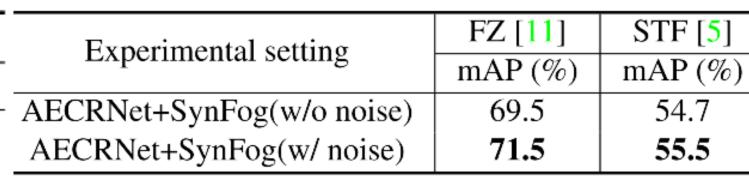
Virtual KITTI

SynFog-β

SynFog (Ours)

Training Set	O-Haze [2]		Foggy Zurich [11]	Foggy Driving [40]	BeDDE [56]	
	PSNR ↑	SSIM ↑	DHQI [14] ↑	DHQI [14] ↑	DHQI [14] ↑	DHQI [14] ↑
Foggy Cityscapes	14.46	0.5737	43.40	52.06	51.55	36.07
Virtual KITTI	13.90	0.5315	42.80	50.94	47.46	33.42
SynFog	15.43	0.6116	44.46	54.16	52.07	43.28

Method	Training Set	FZ [11]	STF [5]
Wicthod	Training Set	mAP (%)	mAP (%)
AECRNet	Foggy Cityscapes	69.7	54.8
	Virtual KITTI	68.9	53.3
	SynFog	71.5	55.5
DehazeFormer	Foggy Cityscapes	67.9	54.9
	Virtual KITTI	68.5	53.1
	SynFog- eta	59.7	55.3
	SynFog	69.7	55.3









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